Debreu’s social equilibrium existence theorem

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Game theory is the study of strategic interaction: how a person should and will behave if her actions affect others and their actions affect her. (We use the term “person” here, but “agent” might be more appropriate, because, in the literature, game theory applies to firms, nations, or even genes, as well as to individual people.) Among fields of application, the theory has had its biggest influence on economics (but has also had considerable sway over political science, evolutionary biology, and computer science, among other disciplines).

Economists are interested in predicting (or at least explaining) behavior in economic environments, for example, what products firms will offer for sale, which goods and services households will purchase, or what securities (e.g., stocks or bonds) investors will trade. To see how game theory has contributed to this effort—and, in fact, has revolutionized economics—think about trying to analyze the behavior of firms in the American automobile industry. To simplify, let’s suppose that the industry is dominated by three companies, General Motors, Ford, and Chrysler (these three did indeed dominate for many years). Now, for General Motors to figure out what models to launch, how many units of each model to produce, and what prices to set for them, it has to anticipate what Ford and Chrysler will be doing. However, the same sort of anticipation is required of Ford and Chrysler. That is, Ford’s best course of action will depend on what it thinks GM and Chrysler are going to do. Actually, it’s even more complex than that, because GM will understand that Ford is trying to forecast GM’s behavior. Therefore, to predict Ford’s actions, GM also has to anticipate Ford’s anticipation, and so on, to higher and higher levels of prediction. Such mutual forecasting is clearly crucial to an analysis of the automobile market but is potentially extremely complex.

Nash’s Contribution

John Nash (1) proposed a simple but powerful concept that cut through this complexity. Because each player in the game (each firm in the automobile industry) is trying to optimize given its anticipation of others’ strategies, he defined an “equilibrium point” (now called a Nash equilibrium) as a fixed point of these optimizations. Specifically, a Nash equilibrium is a configuration of strategies—one for each player—such that no player gains by unilaterally changing its strategy. The concept enormously simplifies the forecasting problem: If each player anticipates that others will use their Nash equilibrium strategies, then it will do so too, and the forecasts will be self-confirming. The success of the Nash equilibrium concept as a predictive and explanatory tool in such settings as the automobile industry transformed much of economics.

Nash equilibrium also helps illuminate behavior in vast array of environments outside economics. To take a simple example, consider how you behaved if you drove to work this morning. If you are in the United States, you probably drove on the right-hand side of the road. Why? Because you anticipated that oncoming drivers would stay to the right, and they anticipated the same of you. These anticipations were self-confirming because everybody driving on the right constitutes a Nash equilibrium; switching to another strategy unilaterally could well be disastrous.

More formally, suppose that there are n players, where each player i (i = 1, ..., n) has a strategy space $S_i$, a set of possible behaviors. In the driving game, for instance, $S_i$ consists of “driving on the right” and “driving on the left.” A game is a function

$$g : S_1 \times \ldots \times S_n \to \mathbb{R}^n,$$

where $g(s_1, \ldots, s_n) = (g_1(s_1, \ldots, s_n), \ldots, g_n(s_1, \ldots, s_n))$, and $g_i(s_1, \ldots, s_n)$ is player i’s payoff when strategies $(s_1, \ldots, s_n)$ are played [when focusing on player i’s payoff, we will sometimes write $(s_1, \ldots, s_i)$ as $(s_i, s_{-i})$, where $s_{-i}$ is the (n − 1)-tuple of the other players’ strategies]. A Nash equilibrium is an n-tuple of strategies $(s_1^*, \ldots, s_n^*) = (s_1^*, s_{-1}^*)$ such that

$$g_i(s_1^*, \ldots, s_n^*) \geq g_i(s_i, s_{-i}^*), \quad i = 1, \ldots, n,$$

and all $s_i \in S_i$. [2]

In words, no player i gains by unilaterally deviating from $s_i^*$ to $s_i$.

Nash (2) showed that a finite game (a game in which each player’s strategy space is finite) has a Nash equilibrium, once players are allowed to randomize over their strategies. Formally, a mixed or randomized strategy for player i is a probability distribution $p_i$ over player i’s pure strategies $S_i$, where for each $s_i \in S_i$, $p_i(s_i)$ is the probability that player i uses strategy $s_i$. If players use mixed strategies $(p_1, \ldots, p_n)$, then, assuming these randomizations are independent across players,

$$\text{player i's expected payoff} = \sum_{s_i \in S_i} \cdot \sum_{s_{-i} \in S_{-i}} g_i(s_1, \ldots, s_n) p_i(s_1) \cdot \ldots \cdot p_n(s_n)$$

$$= g_i(p_1, \ldots, p_n) = g_i(p_{-i}).$$

Nash proved that there exists an n-tuple $(p_1^*, \ldots, p_n^*)$ such that

$$g_i(p_1^*, \ldots, p_n^*) \geq g_i(p_i, p_{-i}^*) \quad \text{for all } i \text{ and } p_i. \quad [3]$$

Nash’s proof was short and simple. For each (n − 1)-tuple $p_{-i}$ of other players’ mixed strategies, let $\psi_i(p_{-i}) = \{p_i|g_i(p_i, p_{-i}) \geq g_i(p_i, p_{-i})\}$ for all $p_{-i}$. The mapping $\psi_i$ is player i’s “best-response” correspondence; $\psi_i(p_{-i})$ consists of all randomized strategies that maximize his payoff given $p_{-i}$. Let $\psi$ be the cross product of the $\psi_i(p_1, \ldots, p_n) = \psi_1(p_1) \times \ldots \times \psi_n(p_n)$. Then, $\psi$ is an upper hemi-continuous, convex-valued, and non-empty-valued correspondence that maps the set of
randomized strategy $n$-tuples to itself. Thus, from the Kakutani fixed point theorem (3), a fixed point $(p_1^*, \ldots, p_n^*) \in \psi(p_1^*, \ldots, p_n^*)$ exists, and, by definition of $\psi$, $(p_1^*, \ldots, p_n^*)$ satisfies Formula 3, i.e., it is a Nash equilibrium.

A serious limitation of Formula 1 is that it assumes that a player’s set of options is not affected by what others do; that is, player $i$’s strategy space $S_i$ does not depend on other players’ strategies. This assumption, admittedly, fits many settings. In the driving game, for example, you are free to drive on the right or left independently of others’ choices (although the consequences of which side you drive on will certainly depend on those choices). However, there are many other games in which the assumption does not make sense. Imagine, for instance, a supermarket shopper interested in buying the basket of goods that is best for her family. Naturally, she can’t choose any basket she pleases; she must stay within her budget. However, this budget is not independent of what other players in the economy do; it will presumably depend, for example, on what her employer pays her. Also, given her budget, which baskets are affordable will depend on the various goods’ prices, which, in turn, are determined by supply and demand in the economy.

Debreu’s Contribution

This is where Gérard Debreu’s “A social equilibrium existence theorem” (4) comes in. Debreu (4) extended the very notion of a game to allow for the possibility that a player’s set of strategies might depend on the strategy choices of other players. Specifically, he supposed that for each player $i$ and each $(n − 1)$-tuple of other players’ strategies $s_{−i}$, player $i$’s choices are limited to some subset $\gamma_i(s_{−i}) \subseteq S_i$; that is, $\gamma_i(s_{−i})$ are the strategies that are feasible for player $i$ when others play $s_{−i}$. In this more general setting, a social equilibrium is an $n$-tuple $(s'_1, \ldots, s'_n)$ such that, for all $i$,

$$s'_i \in \gamma_i(s'_{−i}) \quad \text{[4]}$$

and

$$g_i(s'_1, \ldots, s'_n) \geq g_i(s_i, s'_{−i}) \quad \text{for all } s_i \in \gamma_i(s'_{−i}). \quad \text{[5]}$$

In words, each player, in equilibrium, must be playing a feasible strategy (Formula 4), and no player can gain by unilaterally deviating to some other feasible strategy (Formula 5). Because Debreu was interested in equilibrium in pure strategies, we have not introduced randomizations in Formulas 4 and 5.

Debreu (4) also gave conditions under which a social equilibrium (in pure strategies) is guaranteed to exist. Specifically, he showed that if, for all $i$, $(i) S_i$ is a compact and convex subset of Euclidean space, (ii) $g_i$ is continuous in $(s_i, s_{−i})$ and quasi-concave in $s_i$, i.e., $g_i(\lambda s_i + (1 − \lambda)s'_i, s_{−i}) \geq \min\{g_i(s_i, s_{−i}), g_i(s'_i, s_{−i})\}$ for all $\lambda$ with $0 \leq \lambda \leq 1$, and (iii) $\gamma_i$ is upper and lower hemicontinuous, convex-valued, and non-empty-valued, then there exists an $n$-tuple $(s'_1, \ldots, s'_n)$ satisfying Formulas 4 and 5.

Because Nash (2) was working with randomized strategies, he obtained conditions $i$ and $ii$ automatically: The set of randomizations over a finite strategy set is a compact and convex subset of Euclidean space, and the corresponding payoff function $g_i(p_i, p_{−i})$ is continuous in $(p_i, p_{−i})$ and linear (and hence quasi-concave) in $p_i$. Thus Debreu’s use of conditions $i$ and $ii$ in his proof of existence was a straightforward generalization of Nash. The novel part of Debreu’s argument was his use of the lower hemicontinuity of $\gamma_i$ to show that best-response correspondences are upper hemicontinuous. For all $i$ and $s_{−i}$, let

$$\psi_i(s_{−i}) = \{s_i \in \gamma_i(s_{−i}) | g_i(s_i, s_{−i}) \geq g_i(s'_i, s_{−i}) \}$$

for all $s_i \in \gamma_i(s_{−i})$. The correspondence $\psi_i$ selects player $i$’s feasible best responses to $s_{−i}$, $\psi_i$ is non-empty-valued because $S_i$ is compact, $g_i$ is continuous, and $\gamma_i$ is upper hemicontinuous and non-empty-valued; it is convex-valued because $g_i$ is quasi-concave and $\gamma_i$ is convex-valued [so far, the argument parallels Nash (2)]. To see that $\psi_i$ is upper hemicontinuous, consider a sequence $(s''_1, s''_n) \rightarrow (s_1, s_{−i})$ where, for all $m$, $s''_i \in \psi_i(s''_{−i})$. Now, $s_i \in \gamma_i(s_{−i})$ from the upper hemicontinuity of $\gamma_i$. If $s_i \notin \psi_i(s_{−i})$, there must exist $s_i \in \gamma_i(s_{−i})$ such that $g_i(s_i, s_{−i}) > g_i(s'_i, s_{−i})$. However, because $\gamma_i$ is lower hemicontinuous, there must exist $s''_i \rightarrow s_i$ such that $s''_i \in \gamma_i(s''_{−i})$ for all $m$. Hence, by continuity of $g_i$, $g_i(s'_i, s''_{−i}) > g_i(s''_i, s''_{−i})$ for $m$ big enough, a contradiction of $s''_i \in \psi_i(s''_{−i})$. We conclude that $s_i \in \psi_i(s_{−i})$. Thus, Debreu concludes that $\psi_i$ is upper hemicontinuous, and the Kakutani theorem now applies to give the existence result.

One centrally important application of Debreu’s theorem was to establish the existence of a general equilibrium in a competitive economy. An economy is competitive if the players—the producers and consumers—are too small as individuals to affect market prices. In a general equilibrium of such an economy, the profit-maximizing choices of producers and the preference-maximizing choices of consumers (given equilibrium prices) are consistent in the sense that supply equals demand in every market. Arrow and Debreu (5) laid out the model of a competitive economy and used Debreu’s theorem to show that a general equilibrium exists in this model. The Debreu theorem was of crucial importance here because consumers’ feasible choices in the Arrow–Debreu model depend on their incomes and on prices, as in the supermarket example above.

Debreu (4) succeeded in (i) generalizing the standard framework of game theory by allowing players’ feasible strategy spaces to depend on others’ behavior, (ii) formulating conditions under which a social equilibrium (the natural extension of Nash equilibrium) exists in a generalized game, and (iii) providing the key tool for Arrow and Debreu (5) to establish the existence of a general equilibrium in a competitive economy. For all these reasons, it is a landmark paper.

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