

# Receipt of reward leads to altered estimation of effort

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Edited by Paul W. Glimcher, New York University, New York, NY, and accepted by the Editorial Board September 8, 2015 (received for review April 21, 2015)

**Effort and reward jointly shape many human decisions. Errors in predicting the required effort needed for a task can lead to suboptimal behavior. Here, we show that effort estimations can be biased when retrospectively reestimated following receipt of a rewarding outcome. These biases depend on the contingency between reward and task difficulty and are stronger for highly contingent rewards. Strikingly, the observed pattern accords with predictions from Bayesian cue integration, indicating humans deploy an adaptive and rational strategy to deal with inconsistencies between the efforts they expend and the ensuing rewards.**

effort | reward | retrospective | Bayesian | cue integration

Aye, and I saw Sisyphus in violent torment, seeking to raise a monstrous stone with both his hands.

Homer, Book XI of *The Odyssey*

The adage “it was well worth the effort” highlights an assumed interdependency between attainment of reward and retrospective effort assignment. Despite its ubiquity we know little about the nature of these retrospective effort estimations. Previous studies have focused on the interaction of effort and reward as costs and benefits when a choice is to be made (1–5). Whether receipt of reward influences a retrospective estimation of effort is not known. Intuitively, we assume to have immediate and unbiased access to internal representations of how much “effort” we expended in an endeavor. Here, we demonstrate that retrospective estimation of effort is strongly affected by the amount of monetary reward attained and, as such, is profoundly biased. This bias adheres to established principles of Bayesian cue integration (6–8) and, on this basis, is not irrational.

In a behavioral experiment, participants pressed two buttons on a keyboard to push a ball up a virtual ramp and rated their experienced physical effort in each trial (Fig. 1; see also *SI Materials and Methods* for additional information regarding the task). The ball rolled back by a constant amount on each frame of the display, hence simulating a gravity force that varied so as to manipulate task difficulty ( $n = 6$  difficulty levels, adjusted individually for each participant). Successful trials where participants managed to push the ball all of the way up the ramp were rewarded. Reward was contingent upon task difficulty (with values drawn from six Gaussian distributions with means from 1.5 to 6.5 cents) and the strength of this contingency varied across different blocks of the experiment (SDs of 1.2 or 2.5 cents). Additionally, we included a control experiment in which reward receipt was unrelated to task difficulty ( $SD = \infty$ ).

The reward information was presented either before or after the rating of effort (in 90% and 10% of trials, respectively). Trials in which reward was shown after the estimation of effort served as a reference, because here subjects are not influenced by preceding reward information. Participants were instructed to pay attention to all information presented in a trial, including a brief color change of the ball (50% of the trials), which they needed to detect on each trial. This manipulation was implemented to distract subjects from the true purpose of experiment, discouraging ad hoc strategies that might link effort and reward (also see *SI Materials and Methods*). Twenty-six participants (15 females, age 20–39 y, mean:  $27.07 \pm 5.1$  y) took part in our main

experiment. Two participants were excluded from the analysis because in our debriefing they mentioned they had not paid attention to the reward magnitudes during the experiment. Fourteen participants (nine females, age 21–35 y, mean:  $27.5 \pm 4.1$  y) participated in the control experiment. Participants gave oral and written consent for their attendance. The study was approved by the local ethics committee of Berlin Charité University Hospital.

In trials where reward information was presented before effort rating, we examined whether reward magnitude influenced the effort estimation (Fig. 2). We measured the regression slope between trial-by-trial variations in reward ( $R_i - \mu_r$ , with  $R_i$  being the reward on each trial in cents and  $\mu_r$  being the mean reward of each difficulty level) and estimated effort ( $E_i - \mu_e$ , with  $E_i$  being the estimated effort on each trial and  $\mu_e$  being the mean estimated effort of each difficulty level; see also Fig. S1). In both blocks with different reward contingencies (red vs. blue bars in Fig. 2), there was a significant relationship between reward variation and estimated effort (Wilcoxon sign rank test,  $P = 0.00094$  for  $SD = 1.2$  cents and  $P = 0.002$  for  $SD = 2.5$  cents). This effect of reward on estimated effort was stronger when reward variance was smaller, that is, when reward was highly contingent upon the task difficulty (mean slopes of 0.012 and 0.005 for  $SD = 1.2$  and  $SD = 2.5$  cents, respectively; Wilcoxon sign rank test for the difference of both slopes,  $P = 0.004$ ). This result was highly consistent across subjects (Fig. S2). We observed the same pattern of results when reward magnitude was balanced across blocks using a stratification method (Fig. S3). In a control experiment, where reward was randomly varied and unrelated to the task difficulty ( $SD = \infty$ ), regression slopes did not differ from zero (Wilcoxon sign rank test,  $P = 0.15$ ; for individual data see Fig. S4). These results indicate that reward influences effort

## Significance

Retrospective reevaluation of effort is a pervasive aspect of everyday life, such as when we assess our professional satisfaction after knowing the ensuing outcomes. Previous studies have focused on the interaction of effort and reward when a choice is to be made, whereas retrospective interactions have been largely ignored. Here we show that humans revise their estimation of effort after receiving a reward. When rewarded more than average, subjects tend to overestimate their effort, with a converse effect observed for low rewards. The size of this bias depends strongly on the contingency between reward magnitude and task difficulty and is dynamically adjusted when changes occur in these contingencies. These results reveal a sophisticated mechanism to cope with reward–effort inconsistencies.

Author contributions: A.P. and A.W. designed research; A.P. performed research; A.P. and A.W. analyzed data; and A.P., A.W., and R.J.D. wrote the paper.

The authors declare no conflict of interest.

This article is a PNAS Direct Submission. P.W.G. is a guest editor invited by the Editorial Board.

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This article contains supporting information online at [www.pnas.org/lookup/suppl/doi:10.1073/pnas.1507527112/-DCSupplemental](http://www.pnas.org/lookup/suppl/doi:10.1073/pnas.1507527112/-DCSupplemental).



**Fig. 1.** Participants were asked to move a ball up a ramp by engaging in fast, alternating key presses. A gravity force was simulated, displacing the ball backward by a constant amount on each display frame. We used six levels of task difficulty, corresponding to the amount of ball displacement per time frame. After the ball was successfully pushed all of the way to the top of the ramp, participants received a monetary reward, where reward amount was contingent upon task difficulty. The strength of this contingency was varied in two separate blocks. Reward receipt information was either displayed before (90%) or after the rating of effort (10% of trials, not shown here). Subjects rated their effort by shifting the position of a sliding bar. At the end of each trial, they were asked to indicate whether they had seen a color change in the ball. All intervals in a trial were self-paced except for outcome reward display, which was in view for 2–3 s.

estimation only when there is a reliable relationship with task difficulty, and hence a reliable relationship with the true exertion level subjects expend while pushing the ball.

We next compared our behavioral data to predictions arising out of five separate computational models (Fig. 3). At the time when participants estimate their effort, the requirement was to retrospectively recall their true effort level. This recalled effort,  $E_m$  (gray distribution in Fig. 3A), is predictive of the true effort but is corrupted by noise, as reflected in the variance  $\sigma_m^2$ . When reward is correlated with task difficulty, reward magnitude yields by itself an independent effort estimation  $E_r$  with uncertainty  $\sigma_r^2$  (red distribution in Fig. 3A). In each trial,  $E_r$  and  $E_m$  can differ by a certain amount ( $\Delta E \neq 0$ ). The models we consider are based on distinct ways in which a conflict between these two informational sources ( $E_r$  and  $E_m$ ) might be resolved.

In all models,  $E_m$  is computed based on the trials where reward was presented after the estimation of effort (i.e., where the estimation of effort is unaffected by reward information).  $E_r$  is computed based on the posterior probability distribution of task difficulty given an obtained reward (for details see *SI Materials and Methods*). Model 1 (memory only) assumes that participants solely rely on the recalled effort ( $E_m$ ) and completely ignore reward information. Hence, the effort estimate  $\hat{E}$  is equal to  $E_m$  multiplied by a scaling factor  $k_m$ :

$$\hat{E} = E_m K_m. \quad [1]$$

By contrast, model 2 (reward only) relies completely on reward information, whereas the recalled effort ( $E_m$ ) is disregarded:

$$\hat{E} = E_r K_r. \quad [2]$$

Model 3 assumes that both  $E_m$  and  $E_r$  contribute to effort estimation with  $\hat{E}$  being a weighted average (WA) of  $E_m$  and  $E_r$ :

$$\hat{E} = \omega E_m + (1 - \omega) E_r. \quad [3]$$

Models 1–3 all assume that information regarding each signal's variance is not explicitly exploited by the participants. However, model 4 (Bayes optimal, BO) assumes that a Bayesian optimal strategy is used by the participants where signals are weighted based on their respective reliability or inverse variance:

$$\hat{E} = \omega_m E_m + \omega_r E_r, \quad [4]$$

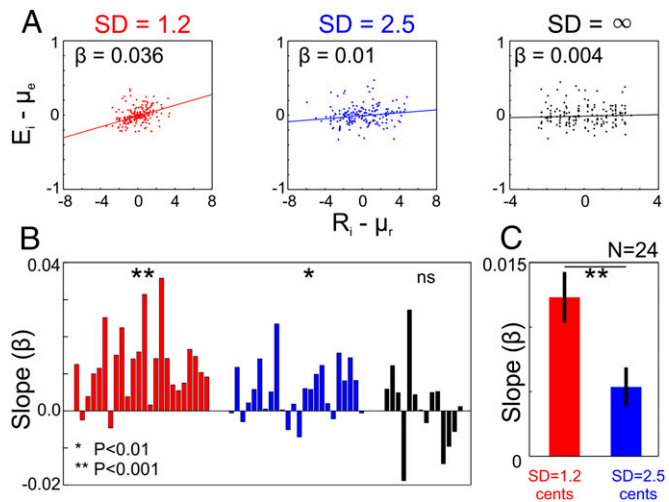
where  $\omega_m = 1 - \omega_r$  and  $\omega_r = 1/\sigma_r^2 / (1/\sigma_m^2 + 1/\sigma_r^2)$ .

Similar reliability-based Bayesian models have been used previously to explain integration of sensory cues during perceptual decision making (6–8). The variances  $\sigma_m^2$  and  $\sigma_r^2$  are derived from the data and reward probability distributions. It is, however, debatable whether  $\sigma_m^2$  is indeed inferred correctly using the trials where reward was presented after the rating of effort. Instead, the

true variance  $\sigma_m^2$  might be a multiple of the variance in these trials. Therefore, model 5 (adapted Bayes optimal, aBO) is a modified version of model 4, assuming that the variance of  $E_m$  ( $\sigma_m^2$ ) is scaled by a free parameter  $k$  ( $\hat{\sigma}_m^2 = k\sigma_m^2$ ):

$$\hat{E} = \frac{\frac{1}{\sigma_r^2}}{\frac{1}{k\hat{\sigma}_m^2} + \frac{1}{\sigma_r^2}} E_m + \left(1 - \frac{\frac{1}{\sigma_r^2}}{\frac{1}{k\hat{\sigma}_m^2} + \frac{1}{\sigma_r^2}}\right) E_r. \quad [5]$$

We evaluated these models by computing their maximum likelihood fits to the trial-by-trial data of individual subjects, measuring the quality of fits by Bayesian information criterion (BIC, *SI Materials and Methods*). BIC weights shown in Fig. 3B are the weight of evidence in favor of each model (9, 10). The average BIC weights are highest for the Bayesian weighted



**Fig. 2.** (A) Relationship between trial-by-trial fluctuations in reward and retrospective estimates of expended effort in a typical subject tested with high ( $SD = 1.2$  cents, data shown in red) and low ( $SD = 2.5$  cents, data shown in blue) reward contingencies. The estimated effort  $E_i$  is normalized to each subject's maximum estimated effort in the whole experiment, and the mean effort  $\mu_i$  of each difficulty level is subtracted. The same procedure is implemented in relation to rewards  $R_i$  and their means  $\mu_r$ . The slope  $\beta$  of the linear regression is larger for the higher reward contingency. In a control experiment, we tested whether random variations of reward ( $SD = \infty$ , data shown in black) affect estimates of effort. Here, slopes did not significantly differ from zero ( $P = 0.15$ ; Wilcoxon sign rank test.) (B) Regression slopes of all individual subjects in both experiments (colors as in A). Average slopes differ from zero only when reward is contingent on task difficulty ( $P$  levels from Wilcoxon sign rank test). (C) Average regression slopes across subjects are higher when reward is more contingent on task difficulty than when less contingent ( $P = 0.004$ , Wilcoxon sign rank test). Error bars denote SEM. Regression results are based on a robust regression analysis ("robustfit" in MATLAB with default settings) that minimizes the effect of potential outliers.





investigation. For example, individuals with higher incomes who are exposed to greater-than-average rewards might have an inflated perception of the effort they expended to acquire their wealth. Conversely, those with low income might have the opposite perception. One might also speculate that such a biased perception of effort could contribute to stabilizing inequality. Indeed, the increasing equality gaps in many societies reinforce the importance of gaining insight into the complex interplay

between retrospective assignments and the emergence of socioeconomic norms.

**ACKNOWLEDGMENTS.** We thank Alexandra Klein, Rafaela Wahl, and Valerie Keller for their help with the data collection, and Ulf Toelch for his advice on the modeling analysis. This work was performed while Ray Dolan was a Visiting Einstein Fellow at the Humboldt-Universität, Berlin School of Mind and Brain and was supported by Wellcome Trust Senior Investigator Award 098362/Z/12/Z (to R.J.D.).

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